

The Virgo GW Detector



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About 20 people in GW group working on GW theory, data analysis, multi-messenger science, instrument science.



Program for today:

- **Seismic environment of Virgo**
- **Gravitational coupling between seismic field and test masses**
- **Mitigation of Newtonian noise**

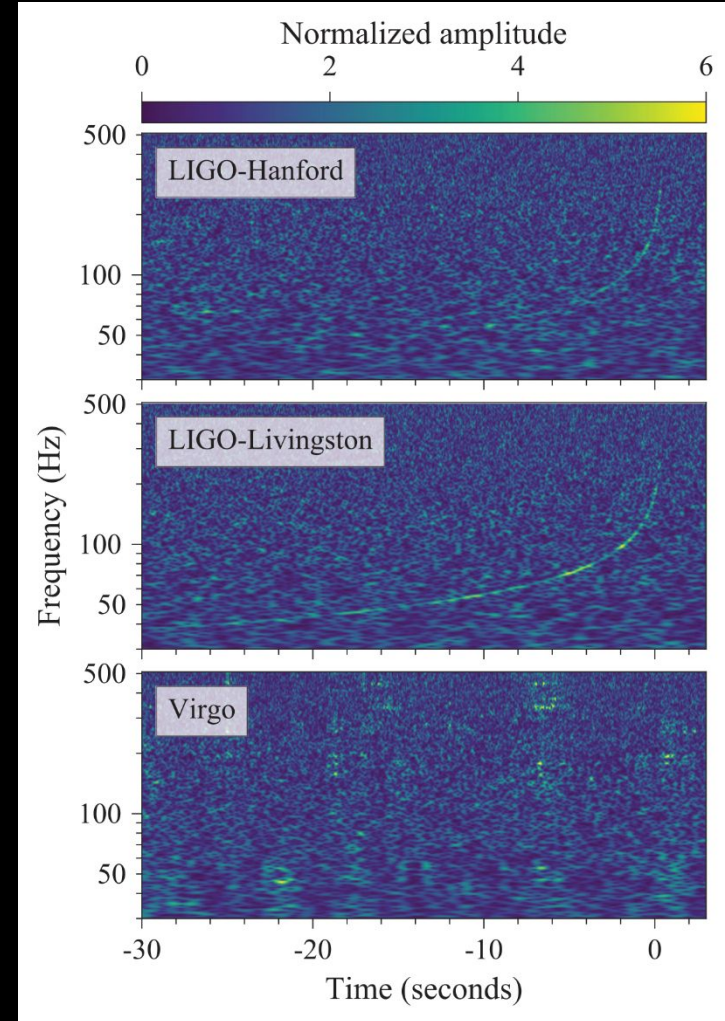




Construction started in 1996.

First GW observations in 2017.

GW170817



Alain Brillet

Adalberto

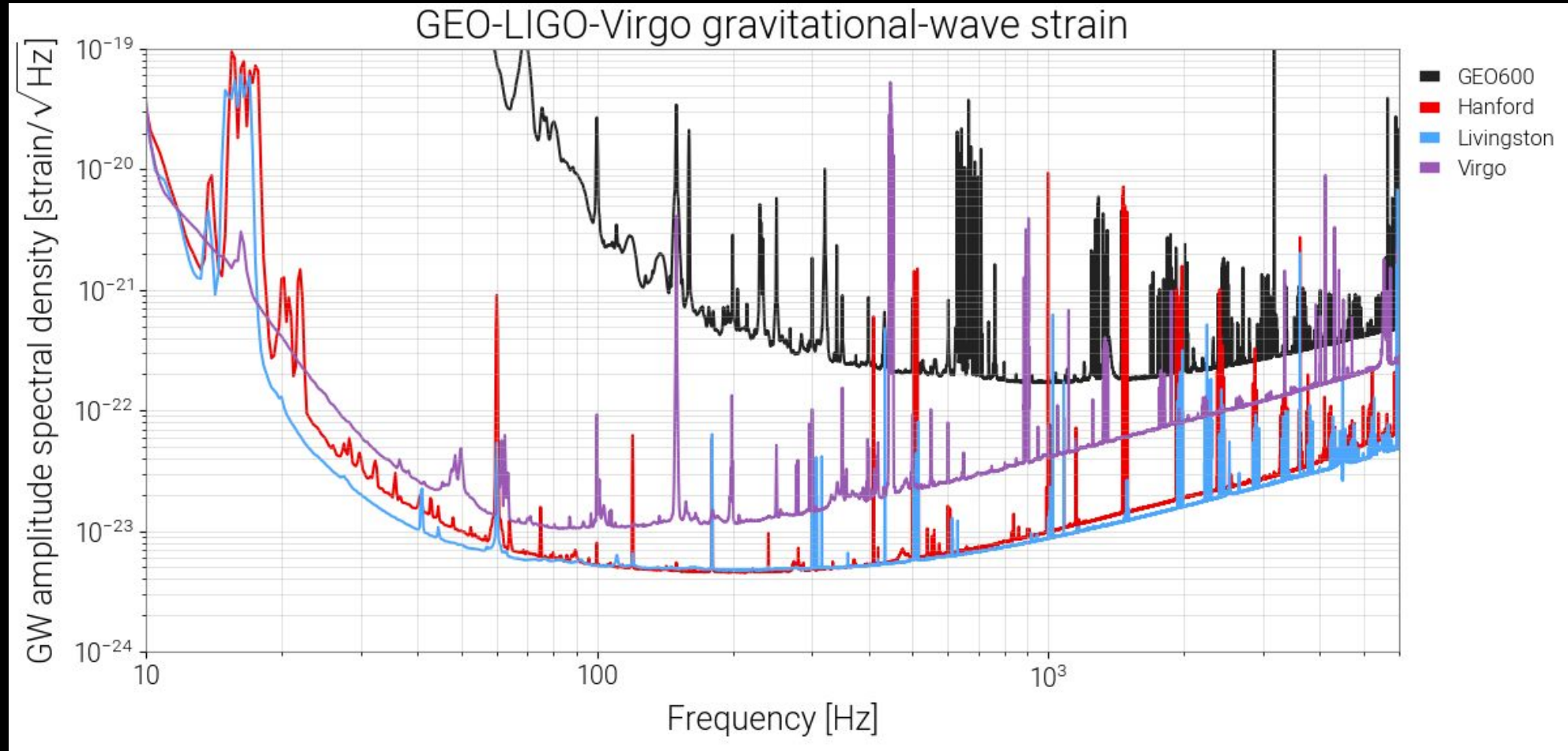


07/28/2022

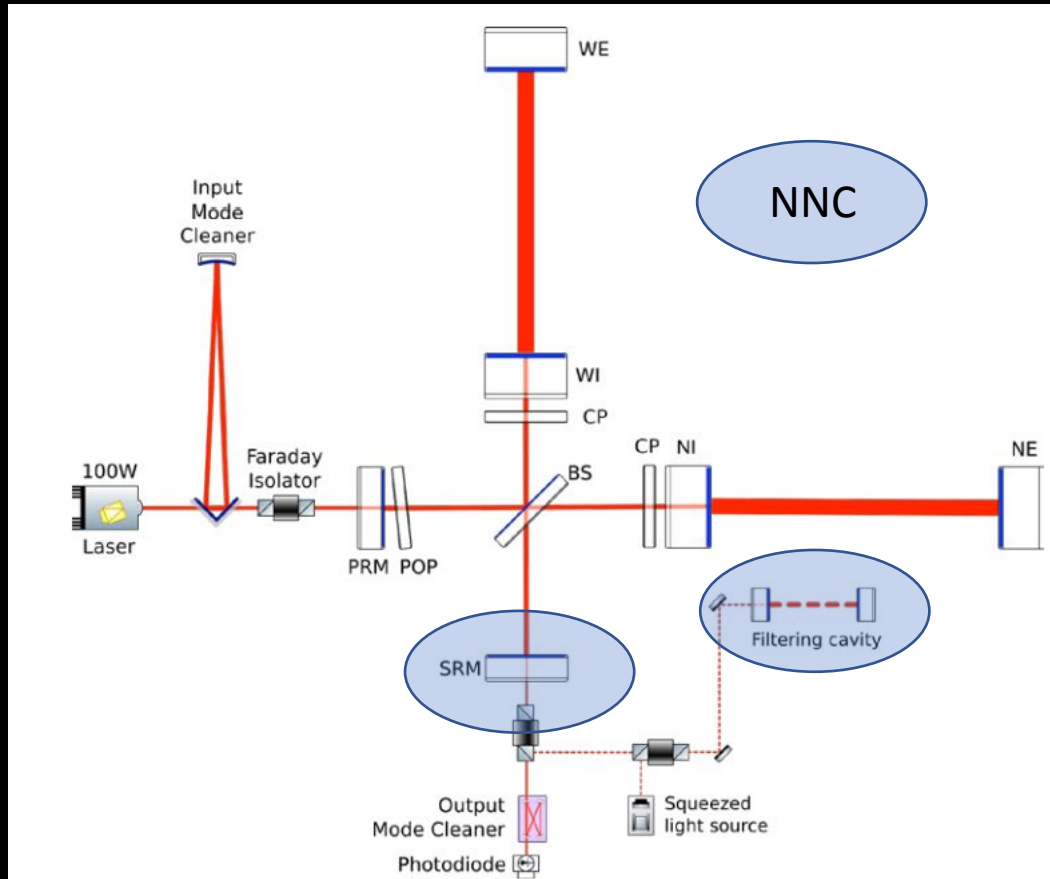


The Virgo Detector; J Harms

End of O3



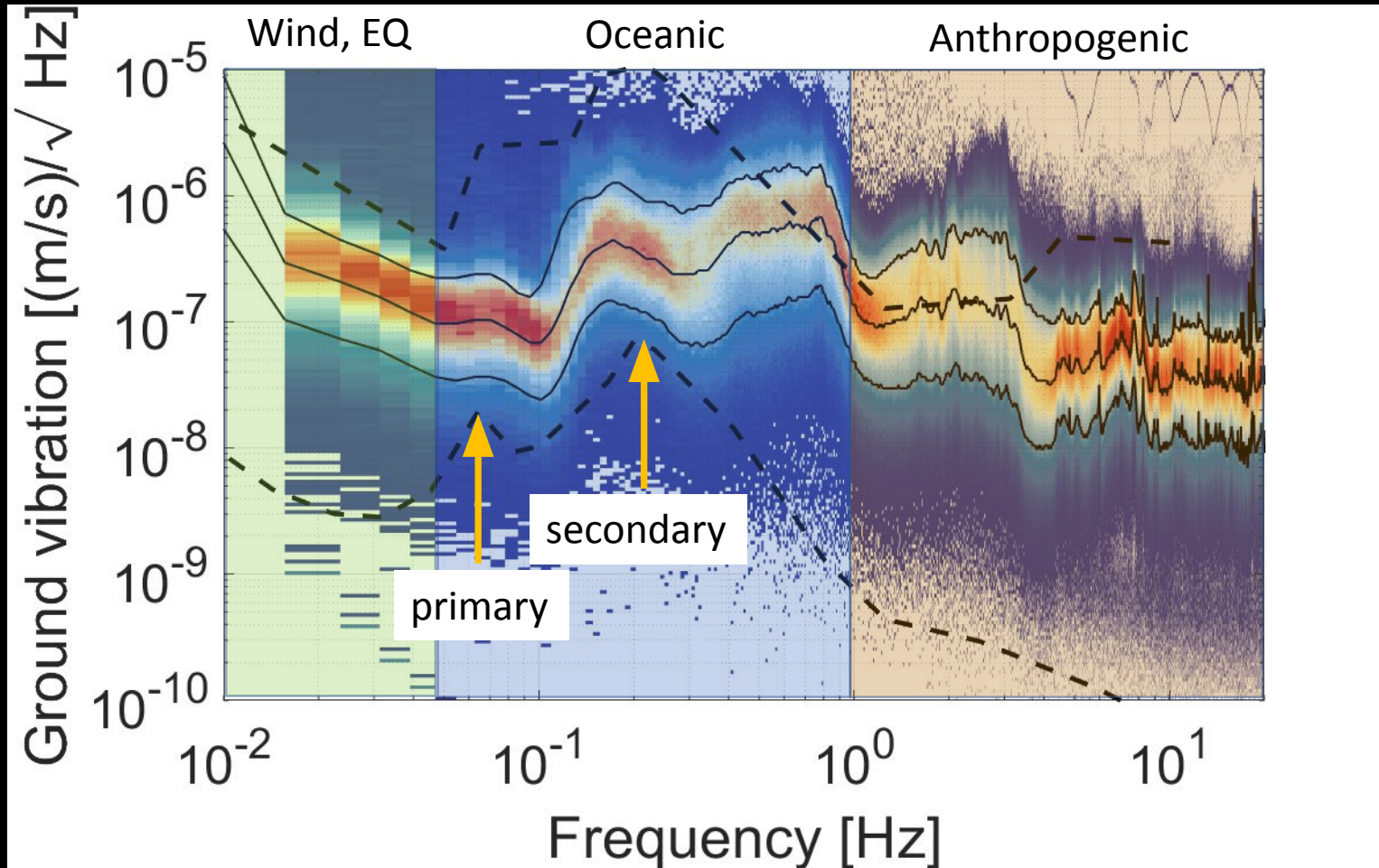
Virgo will have a new look in O4: AdV+ Phase I



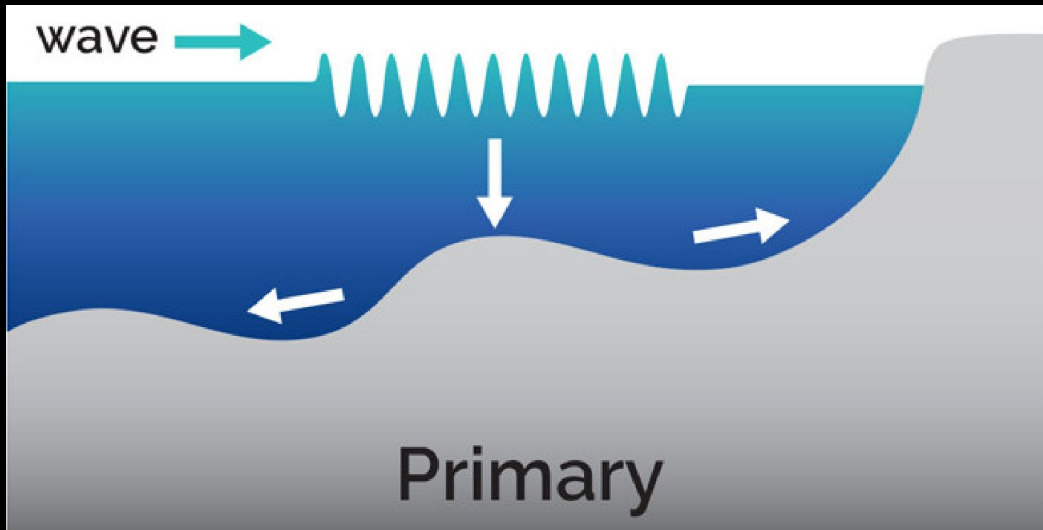
Configuration changes

- Interferometer has a signal-extraction mirror
- Interferometer has a squeezed-light filter cavity
- Detector augmented by a Newtonian-noise cancellation system

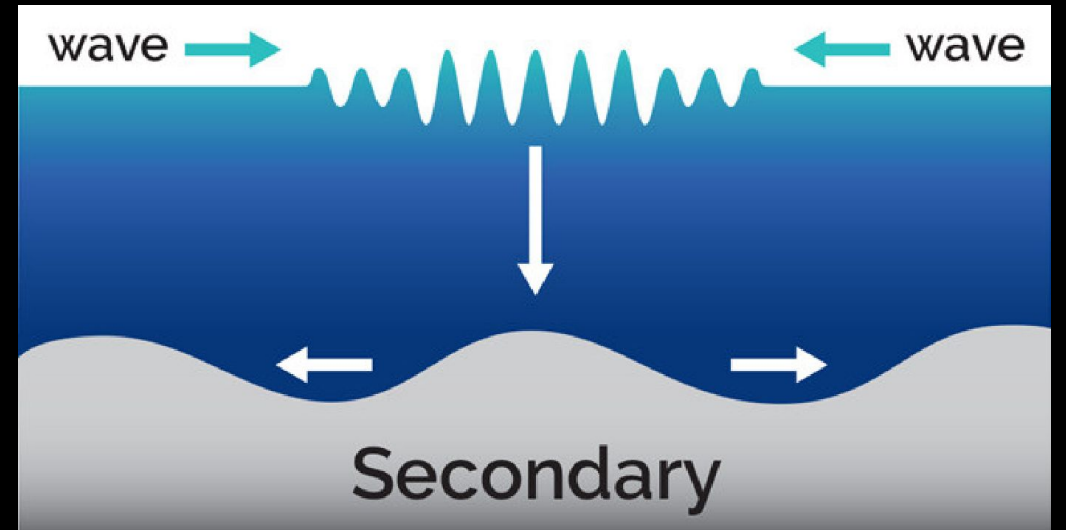
Virgo seismic noise



In shallow waters, the evanescent pressure field under waves couples to sea floor.



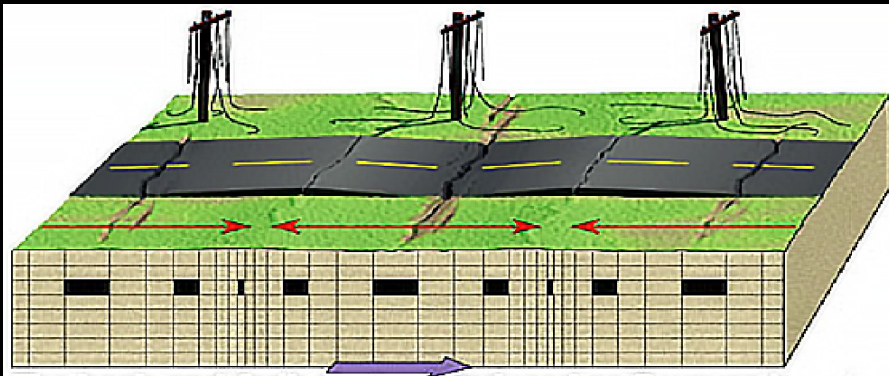
In deeper waters, standing ocean waves can emit pressure waves, which interact with sea floor.



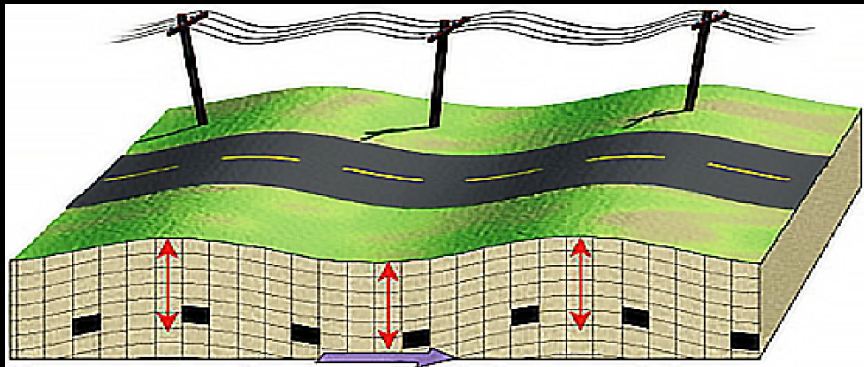
Seismic waves

Body waves

Compressional waves (P)

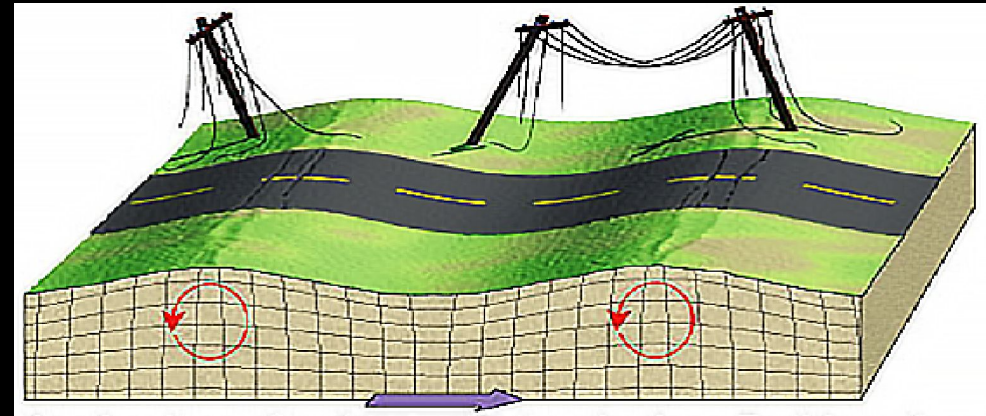


Shear waves (S)



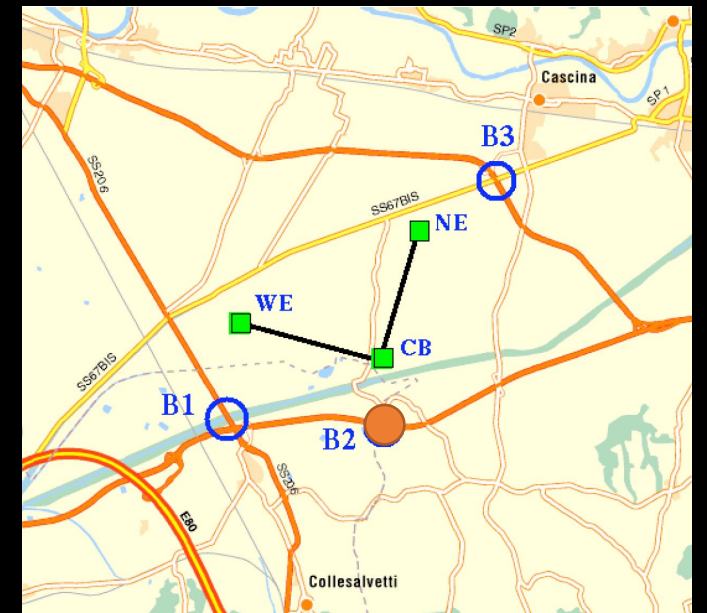
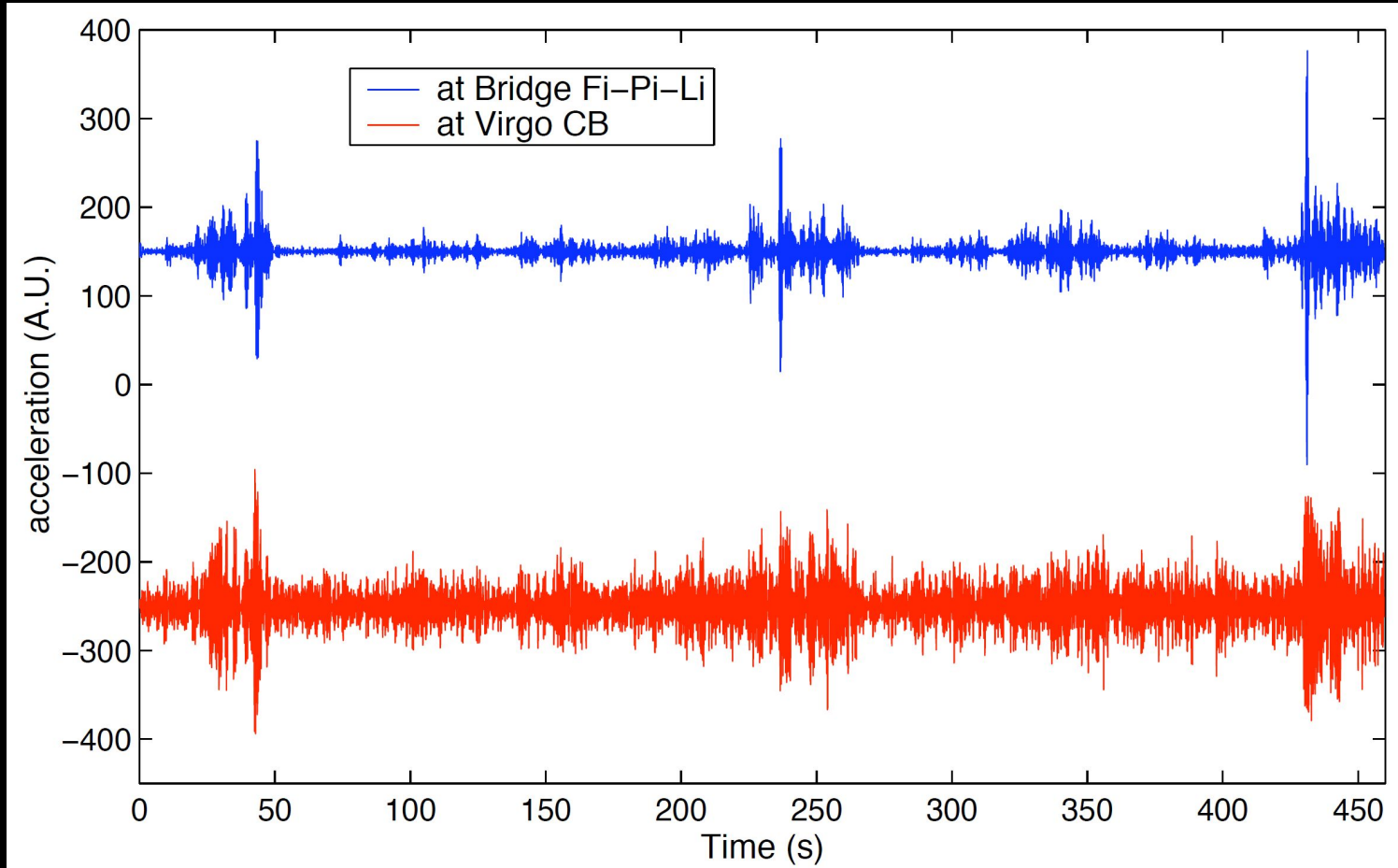
Surface waves

Rayleigh waves

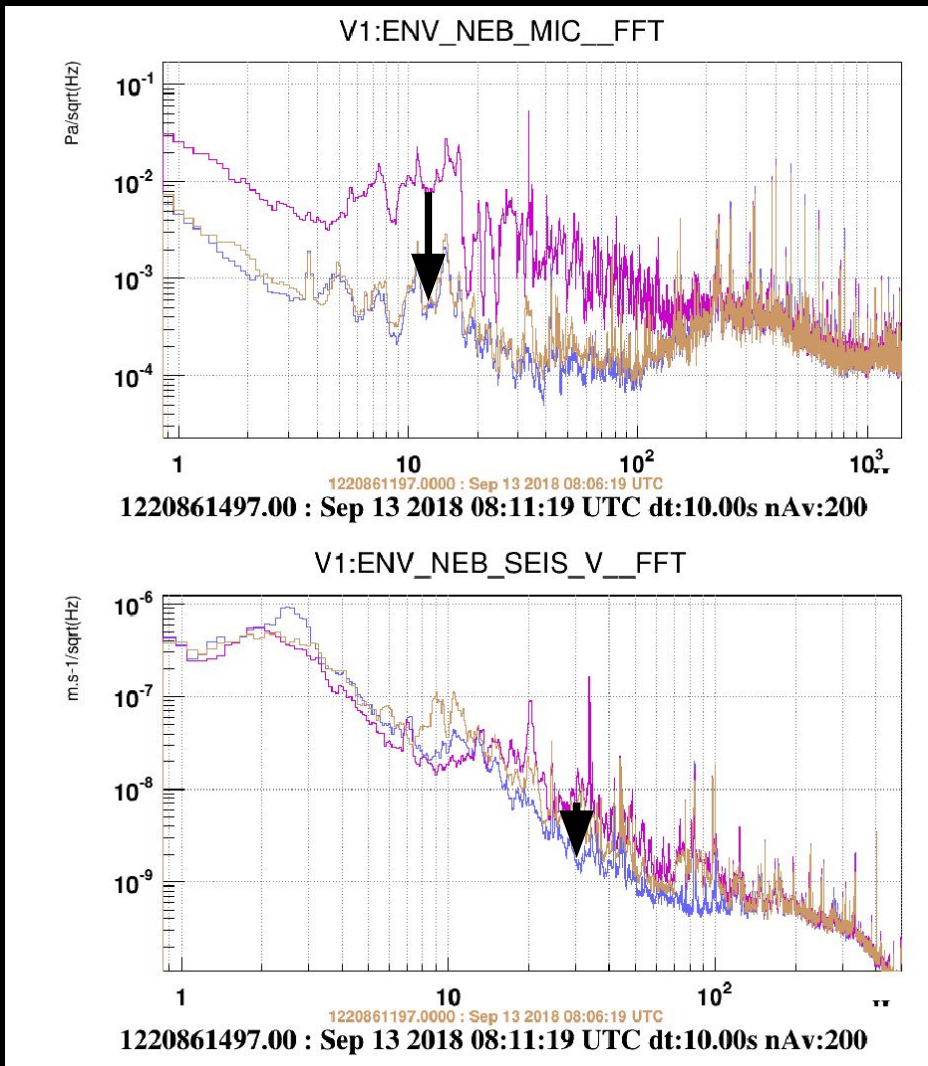


Rayleigh waves typically dominate seismic displacement at the surface.

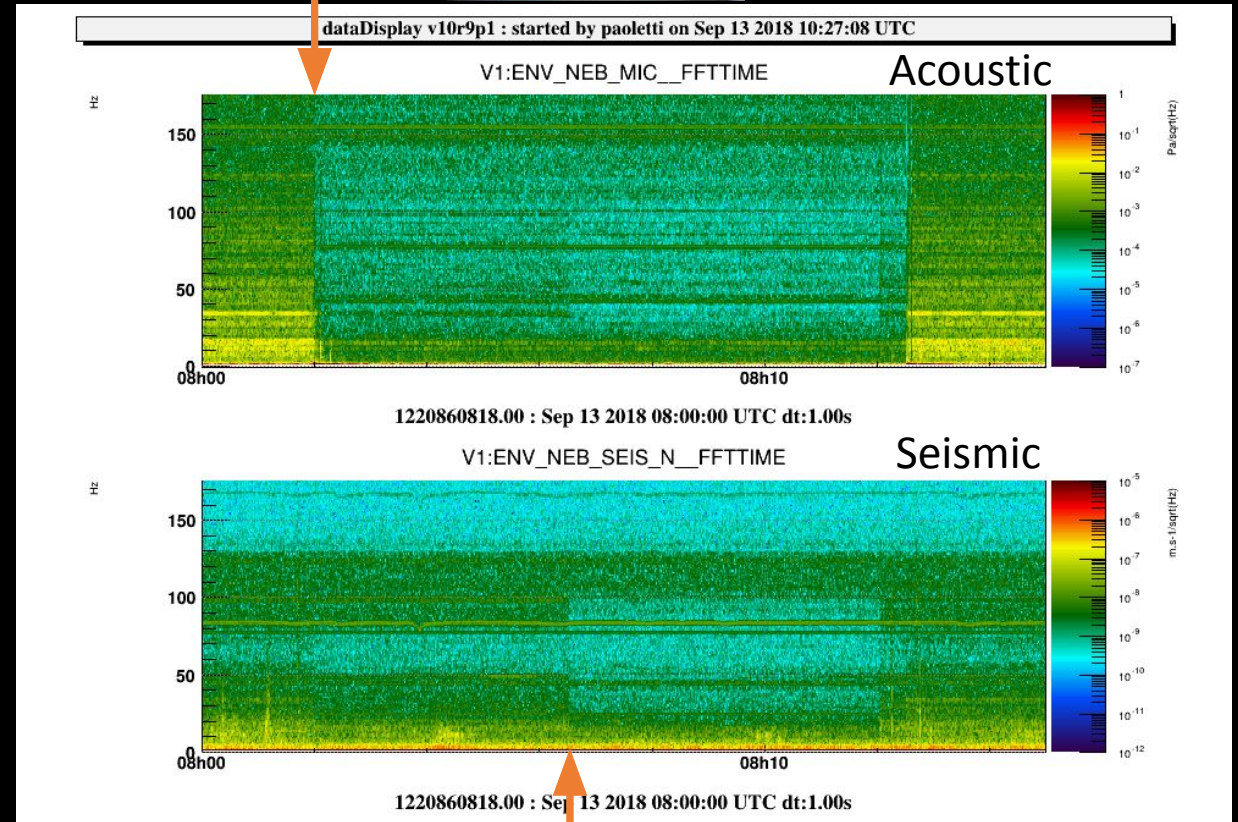
Trucks passing highway bridge



Ventilation switch-off test



Airflow off



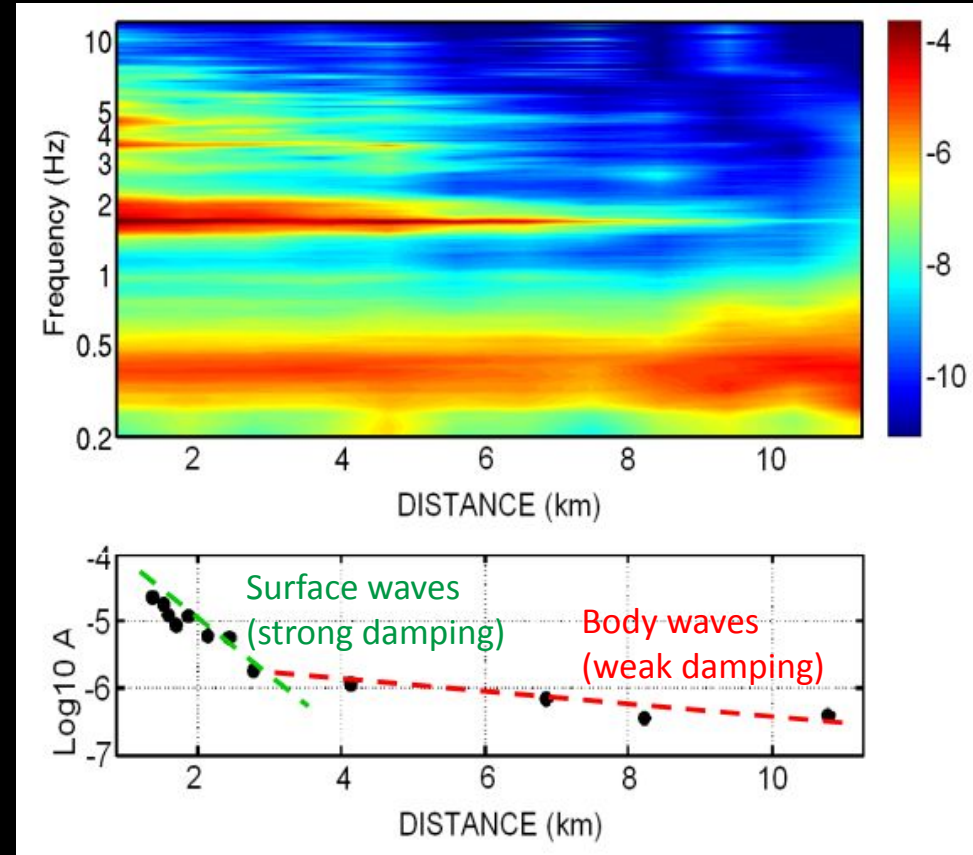
HVAC off



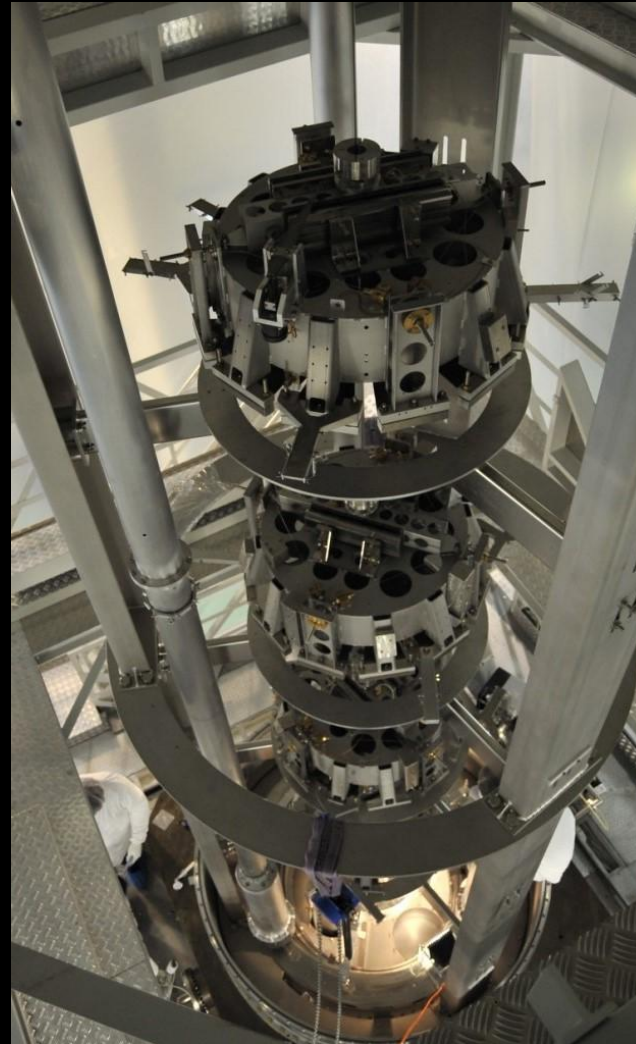
Wind turbines at 6km to Virgo buildings



Wind turbines are a strong source of acoustic and seismic noise detectable over several kilometers.



Virgo superattenuator

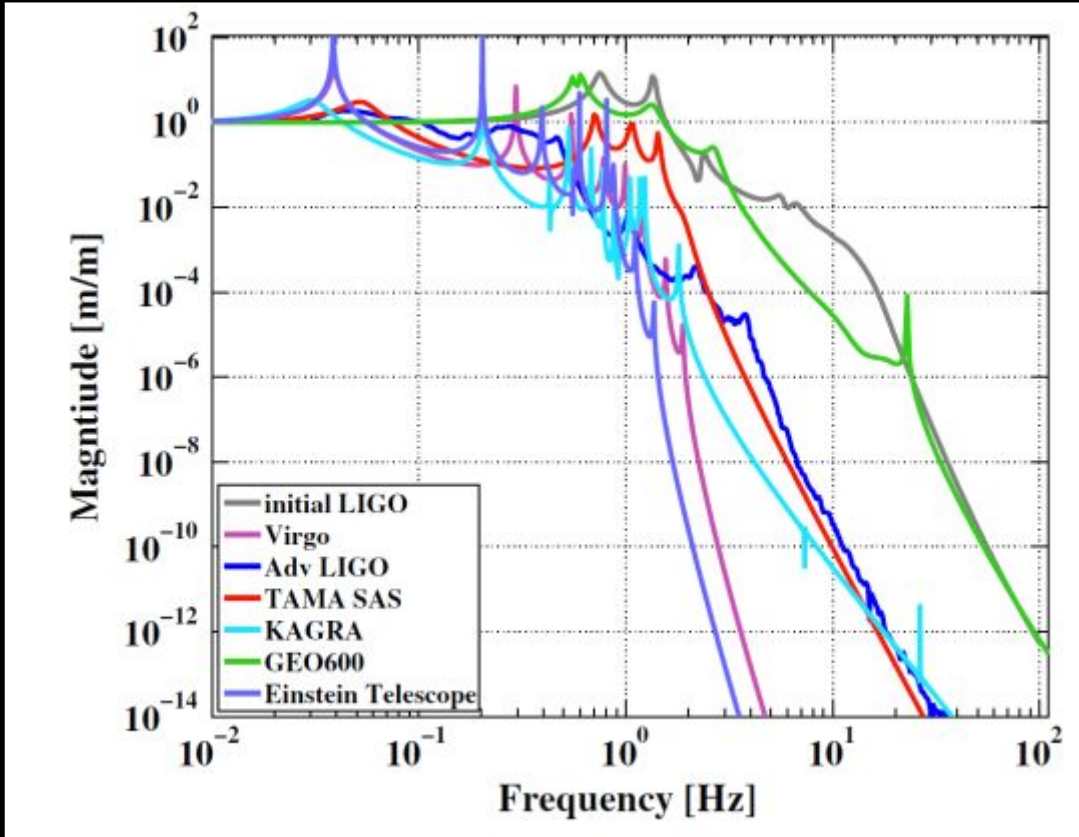


An iconic component of the Virgo detector is the superattenuator inside the 10m tall towers.

It is a design choice initially made to enable low-frequency GW observations.

Virgo seismic isolation

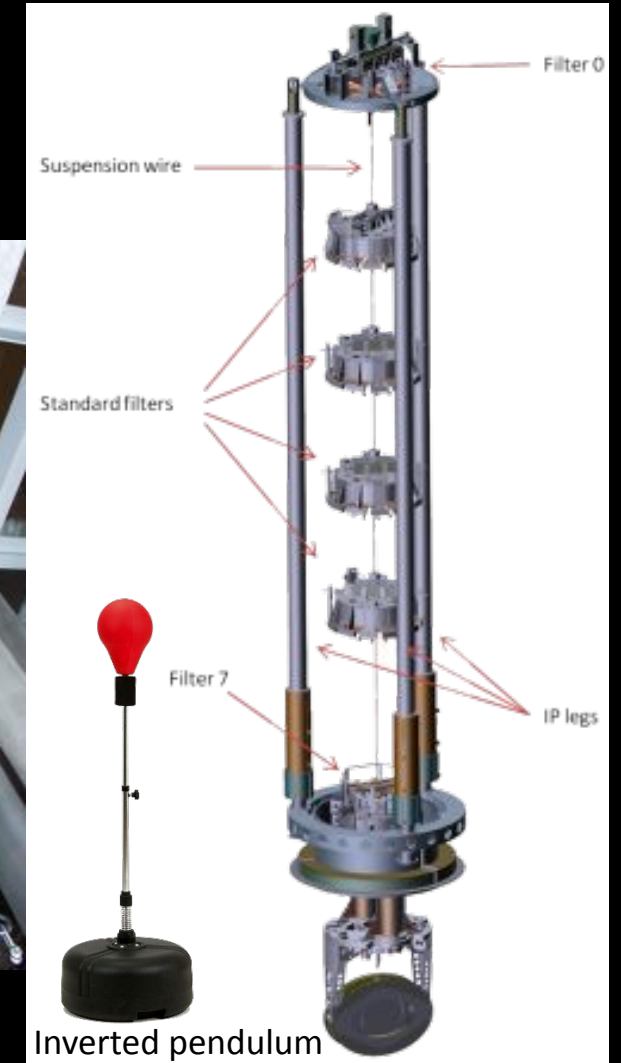
Seismic isolation



Mechanical filters

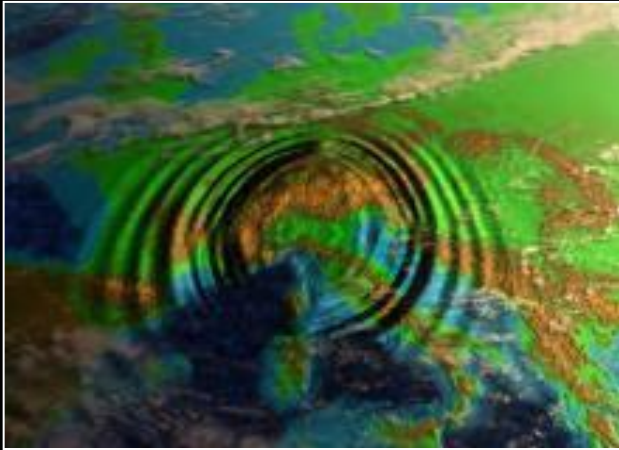


Superattenuator



Gravitational fluctuations

Seismic



$$\frac{\xi(f)}{f^2} e^{-2\pi f h / c_{\text{seis}}}$$

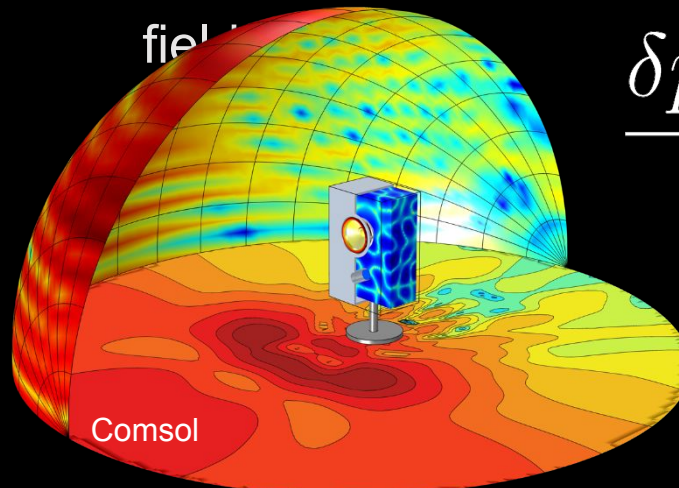
Advected temperature fields

Mellado, 2017



$$\frac{\delta T(f)}{f^{10/3}} e^{-2\pi f r / v}$$

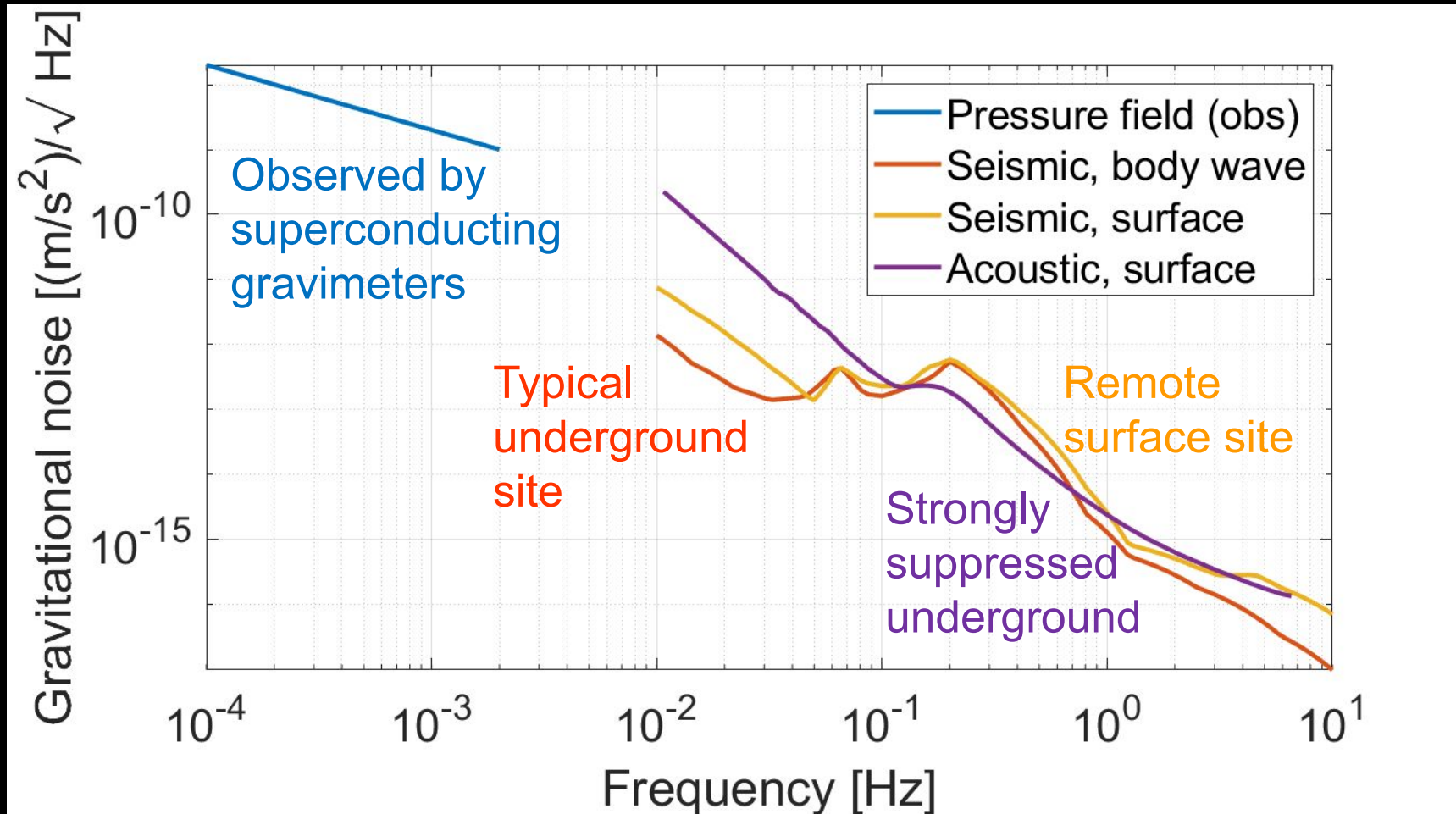
Infrasound field



Comsol

$$\frac{\delta p(f)}{f^3} e^{-2\pi f d / c_{\text{snd}}}$$

Gravity spectra



Linearized density perturbation

$$\delta\rho(\vec{r}, t) = -\nabla \cdot \left(\rho(\vec{r}) \vec{\xi}(\vec{r}, t) \right)$$



Neglect time variations of density here

Homogeneous medium

$$\delta\phi_{\text{bulk}}(\mathbf{r}_0, t) = G\rho_0 \int_{\mathcal{V}} dV \frac{\nabla \cdot \xi(\mathbf{r}, t)}{|\mathbf{r} - \mathbf{r}_0|}$$

+

$$\delta\phi_{\text{surf}}(\mathbf{r}_0, t) = -G\rho_0 \int dS \frac{\mathbf{n}(\mathbf{r}) \cdot \xi(\mathbf{r}, t)}{|\mathbf{r} - \mathbf{r}_0|}$$

Bulk term: (de)compression

Surface term: normal surface displacement

Simplest analytical models

Body-wave NN

$$\begin{aligned}
 C_{\text{NN}} &= \left(\frac{4}{3}\pi G\rho_0\right)^2 [4\langle(\vec{e}_{\text{tm}} \cdot \vec{\xi}^{\text{P}}(\vec{r}_0, \omega))^2\rangle + \langle(\vec{e}_{\text{tm}} \cdot \vec{\xi}^{\text{S}}(\vec{r}_0, \omega))^2\rangle] \\
 &= \left(\frac{4}{3}\pi G\rho_0\right)^2 S(\xi; \omega)(3p + 1)
 \end{aligned}$$

Surface and Rayleigh-wave NN

$$C_{\text{NN}} = \frac{1}{2} (2\pi\gamma G\rho_0 \exp(-2\pi h/\lambda))^2 S(\xi; \omega)$$

How to obtain these equations:

- Calculate the gravitational perturbation caused by a single plane wave
- Average over propagation directions

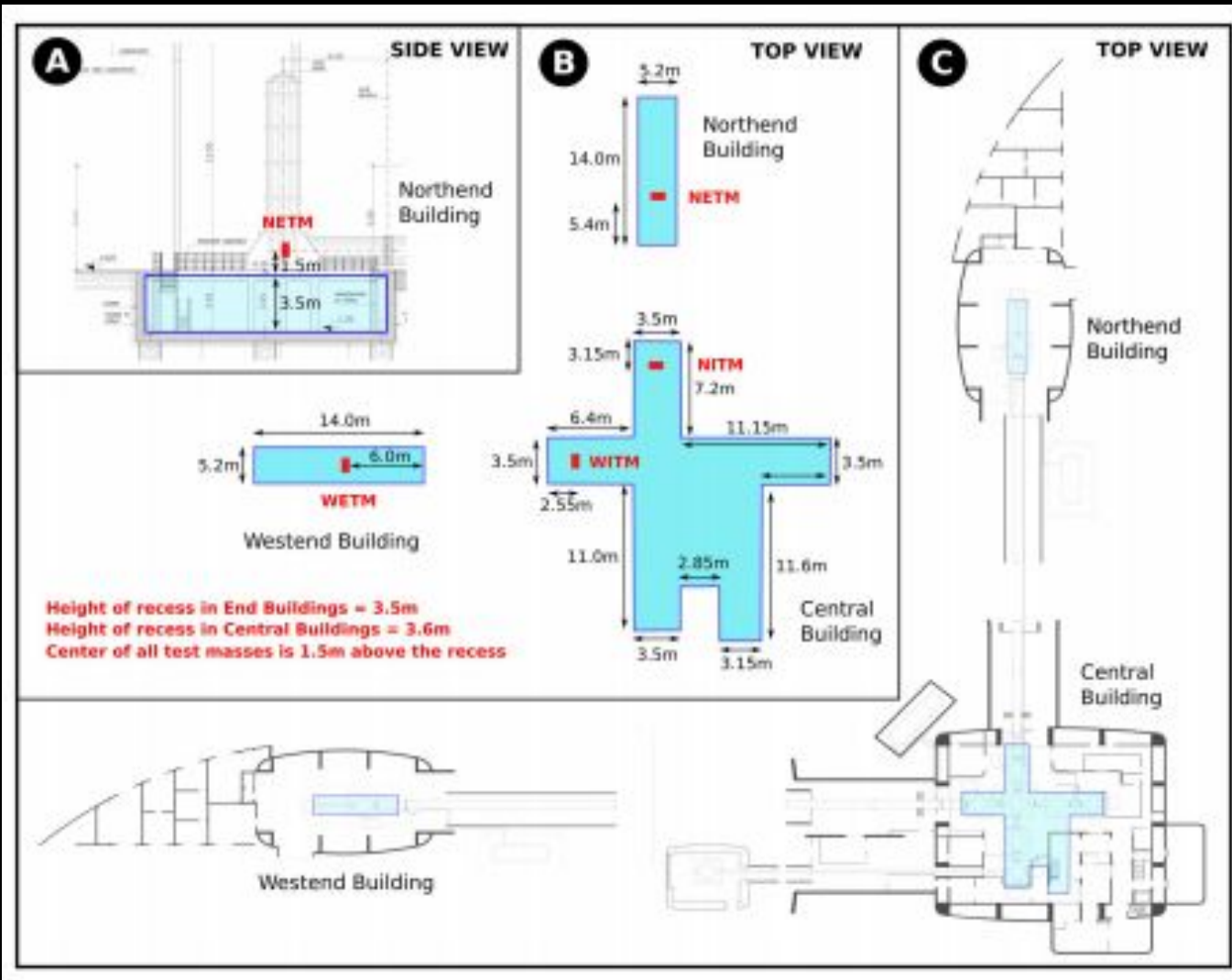
Simplest numerical models

Dipole equation (oscillating mass elements)

$$\begin{aligned} \delta \mathbf{a}(\mathbf{r}_0, t) &= -G \int dV \rho(\mathbf{r}) (\boldsymbol{\xi}(\mathbf{r}, t) \cdot \nabla_0) \cdot \frac{\mathbf{r} - \mathbf{r}_0}{|\mathbf{r} - \mathbf{r}_0|^3} \\ &= G \int dV \rho(\mathbf{r}) \frac{1}{|\mathbf{r} - \mathbf{r}_0|^3} (\boldsymbol{\xi}(\mathbf{r}, t) - 3(\mathbf{e}_{rr0} \cdot \boldsymbol{\xi}(\mathbf{r}, t))\mathbf{e}_{rr0}) \end{aligned}$$

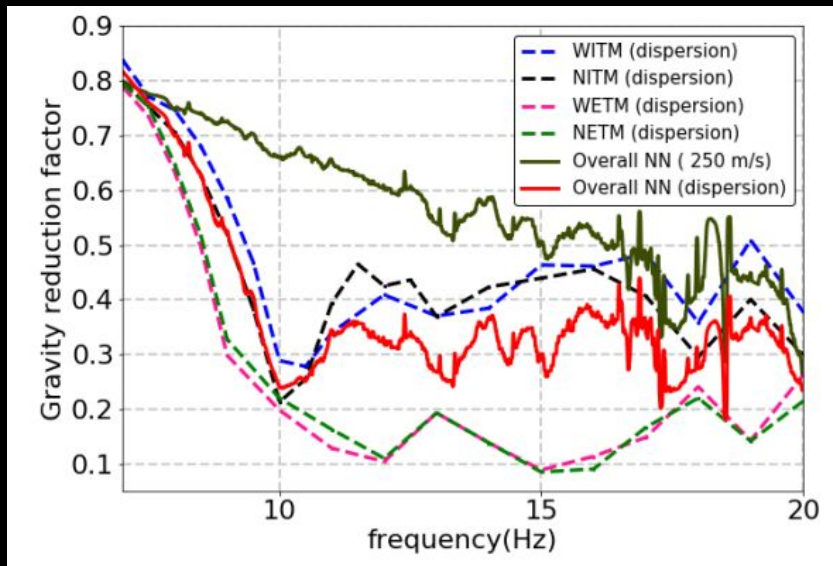
Method

- Propagate waves of known analytical form through a finite-element model
- Numerically integrate the associated gravity perturbation using the dipole equation



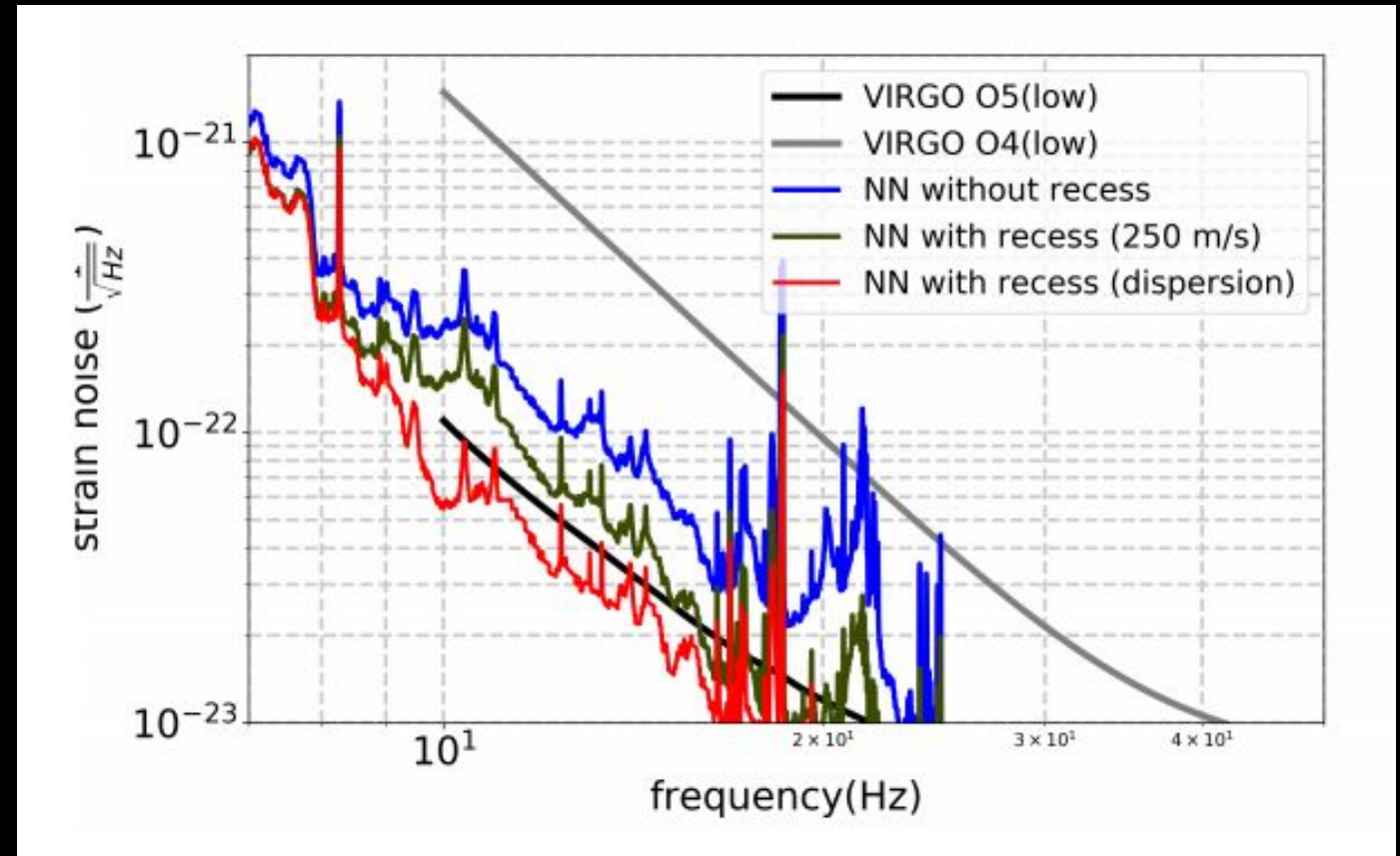
This type of simple numerical analysis was used for the current Virgo NN estimate (matches Bayesian estimate).

It takes into account the presence of clean rooms under the towers.



Lucky! Twice!

- Clean rooms under the towers increase distance between test masses and ground
- In the 10-20Hz band, the dominant seismic waves are extremely slow (<100m/s)



Singha et al (2021)

Numerical models based on seismic correlations

Example: surface NN, homogeneous model

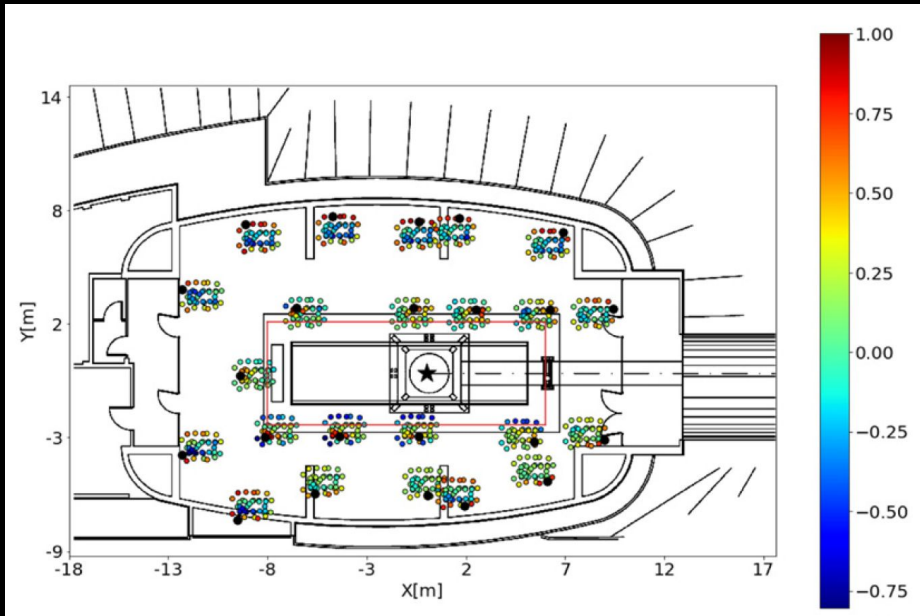
$$S(\delta a_x; \omega) = (2\pi G \rho_0 \gamma(v))^2 \frac{1}{2\pi} \int d^2 \varrho \left[\frac{x^2}{\varrho^2} \frac{2h}{((2h)^2 + \varrho^2)^{3/2}} + \frac{y^2 - x^2}{\varrho^4} \left(1 - \frac{2h}{((2h)^2 + \varrho^2)^{1/2}} \right) \right] C(\xi_z; \varrho, \omega)$$

Seismic correlations

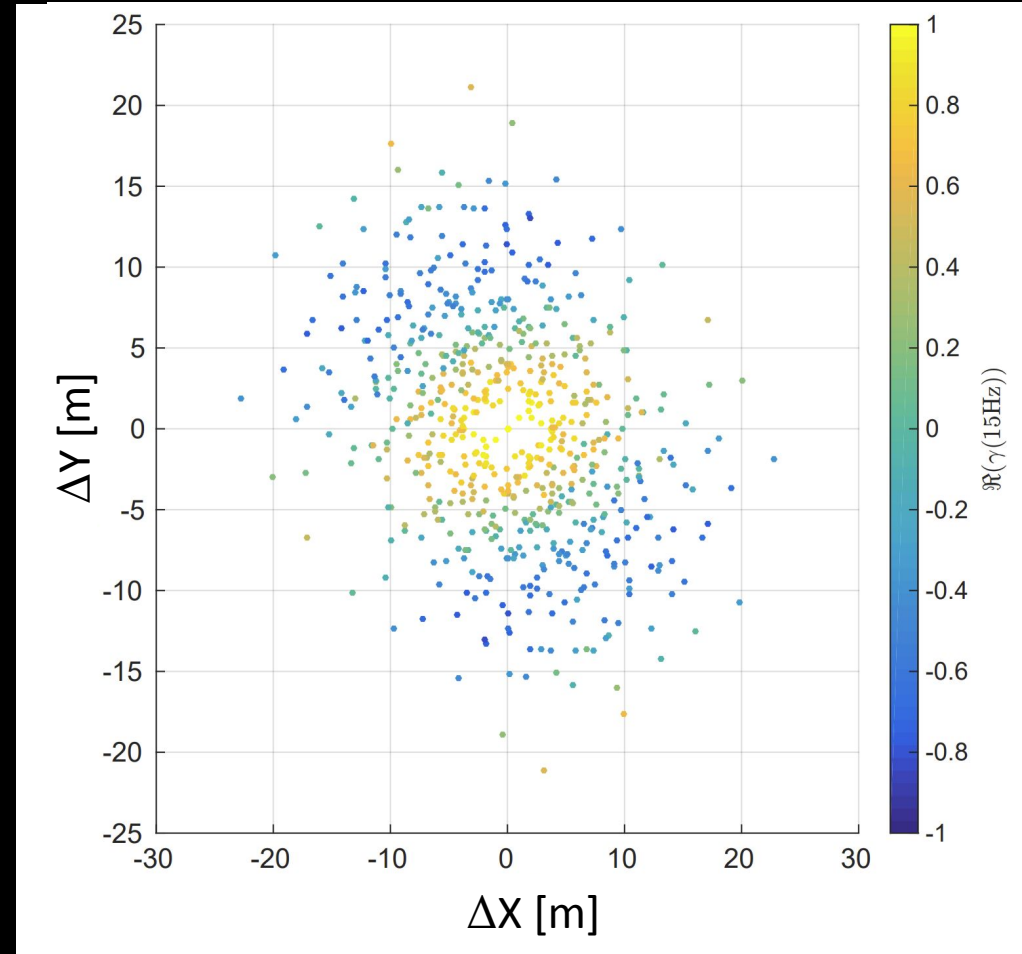
Method

- Use observed seismic correlations
- Integrate numerically using an appropriate kernel

Seismic correlations at Virgo

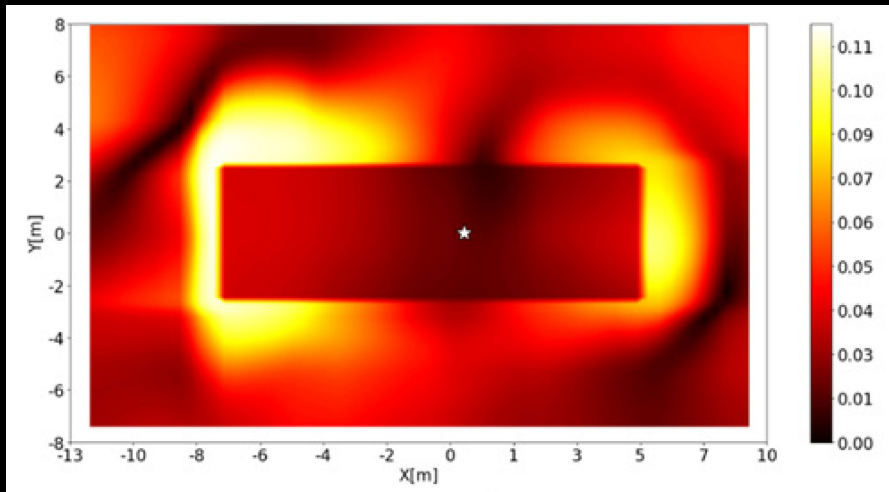


Seismic correlations at LIGO



Coughlin et al (2018)

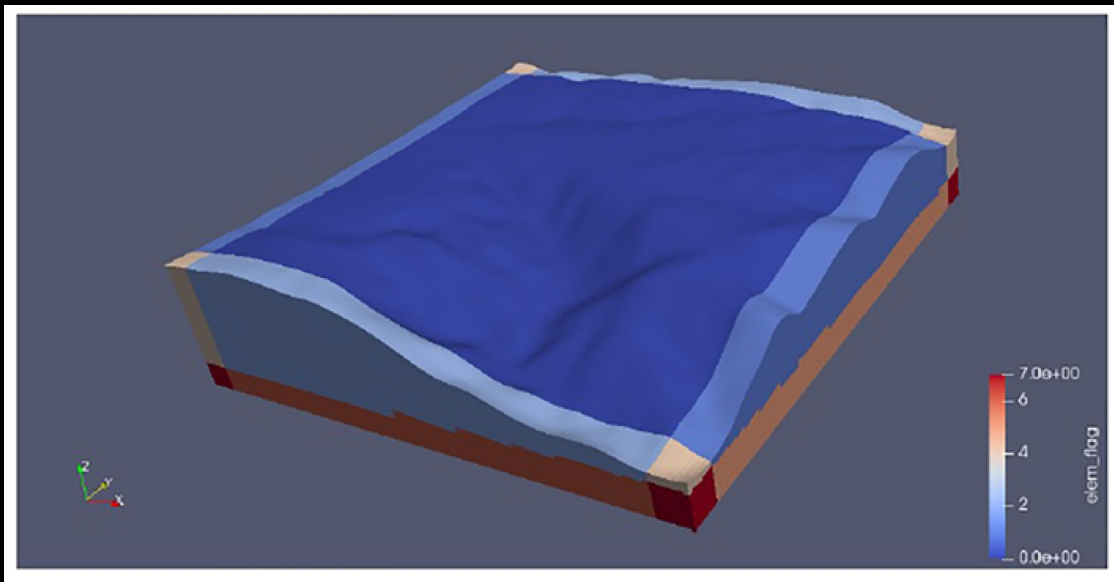
Modeled gravitational coupling



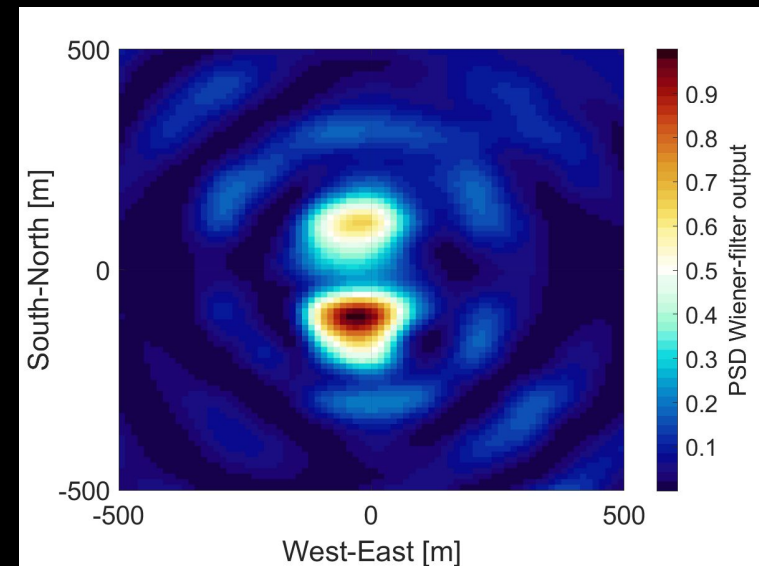
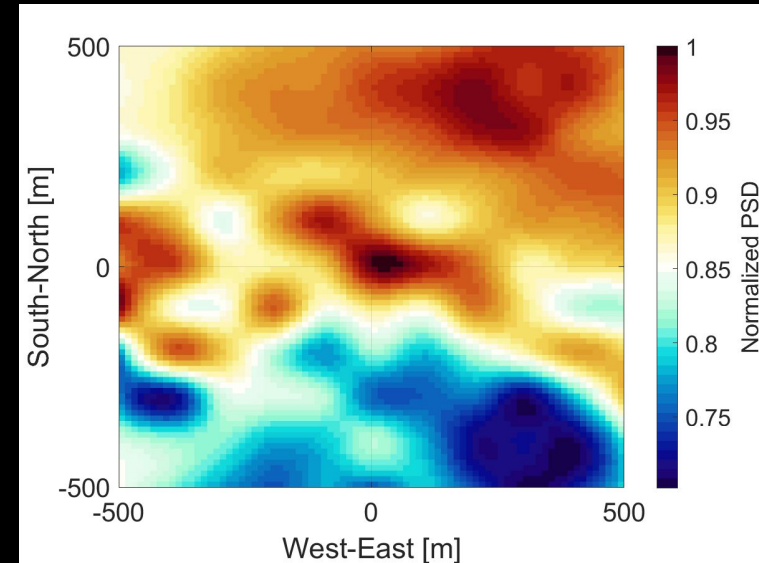
Badaracco et al (2020)

Dynamical finite-element simulations

Any scenario can in principle be modelled



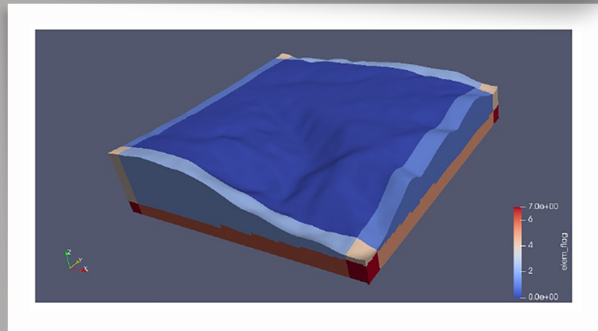
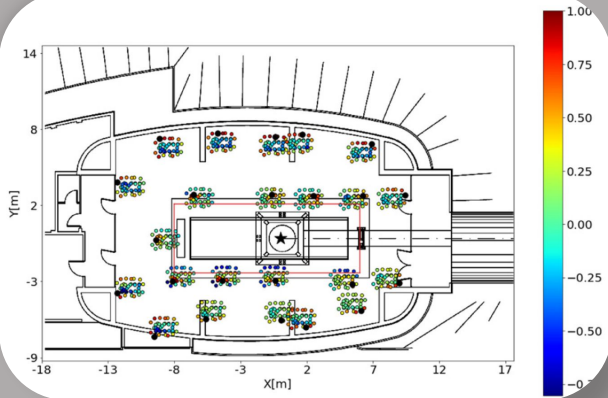
Example: site in Sardinia



Andric/Harms (2020)

Bayesian NN estimation

Combine models and measurements

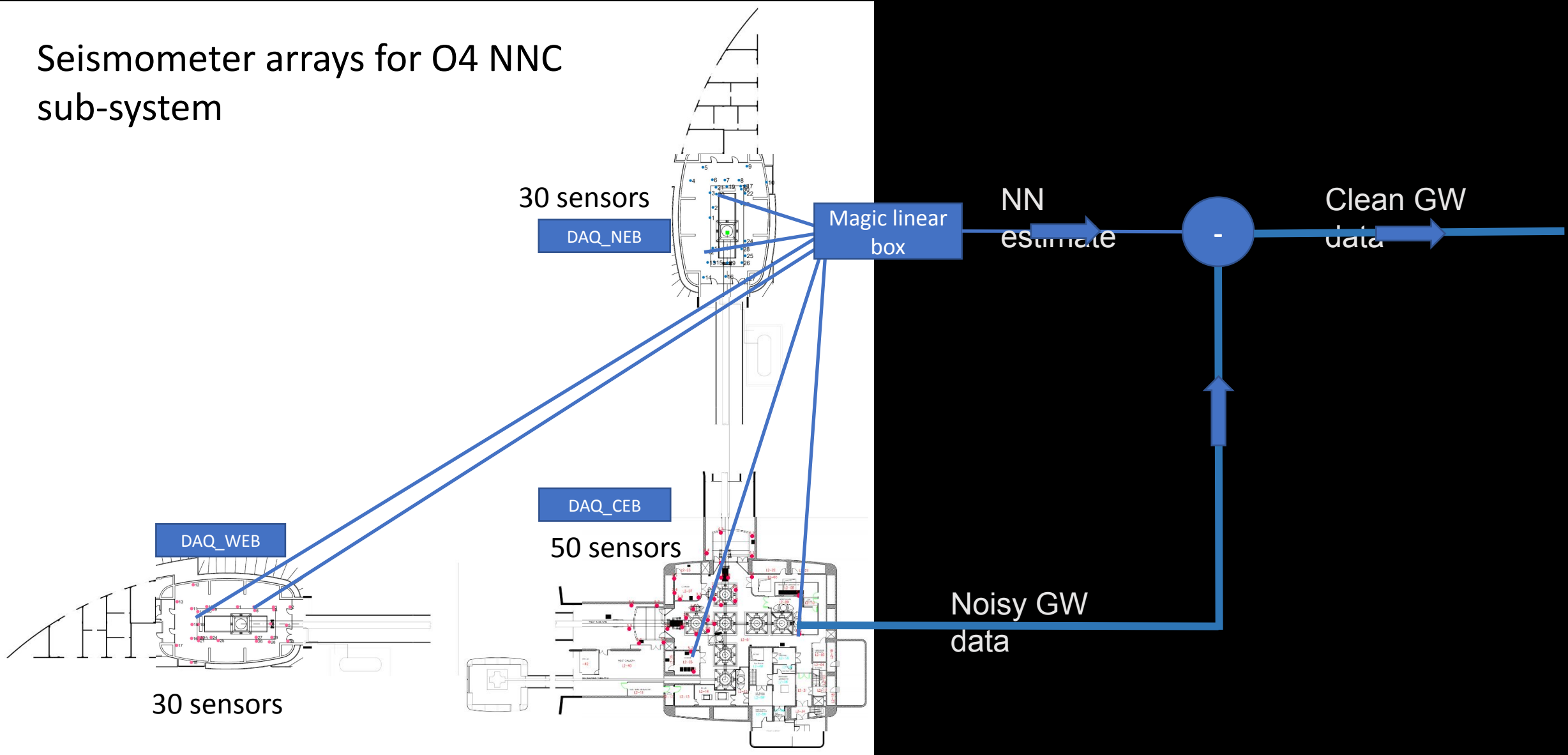


Method

1. Measure seismic correlations
2. Model seismic correlations, e.g., with SPEC-FEM3D
3. Set up surrogate model of seismic correlations (e.g., using GPR)
4. Numerically integrate surrogate model with appropriate kernel to obtain Newtonian noise

NN cancellation at Virgo

Seismometer arrays for O4 NNC sub-system



Linear noise cancellation

Wiener filter

$$\mathbf{C}_{xx} \cdot \mathbf{w}(:) = \mathbf{C}_{xy}$$

Seismometer
correlation matrix

Correlations between
seismometers and GW data

- Requires estimate of a huge number (up to millions) of correlation coefficients (large statistical error)
- Filter is stationary

Finite-impulse response (FIR) filter

$$\hat{y}_n = \sum_{k=0}^N \mathbf{w}_k \cdot \mathbf{x}_{n-k}$$

$$\equiv \mathbf{w} \circ \mathbf{x}_n$$

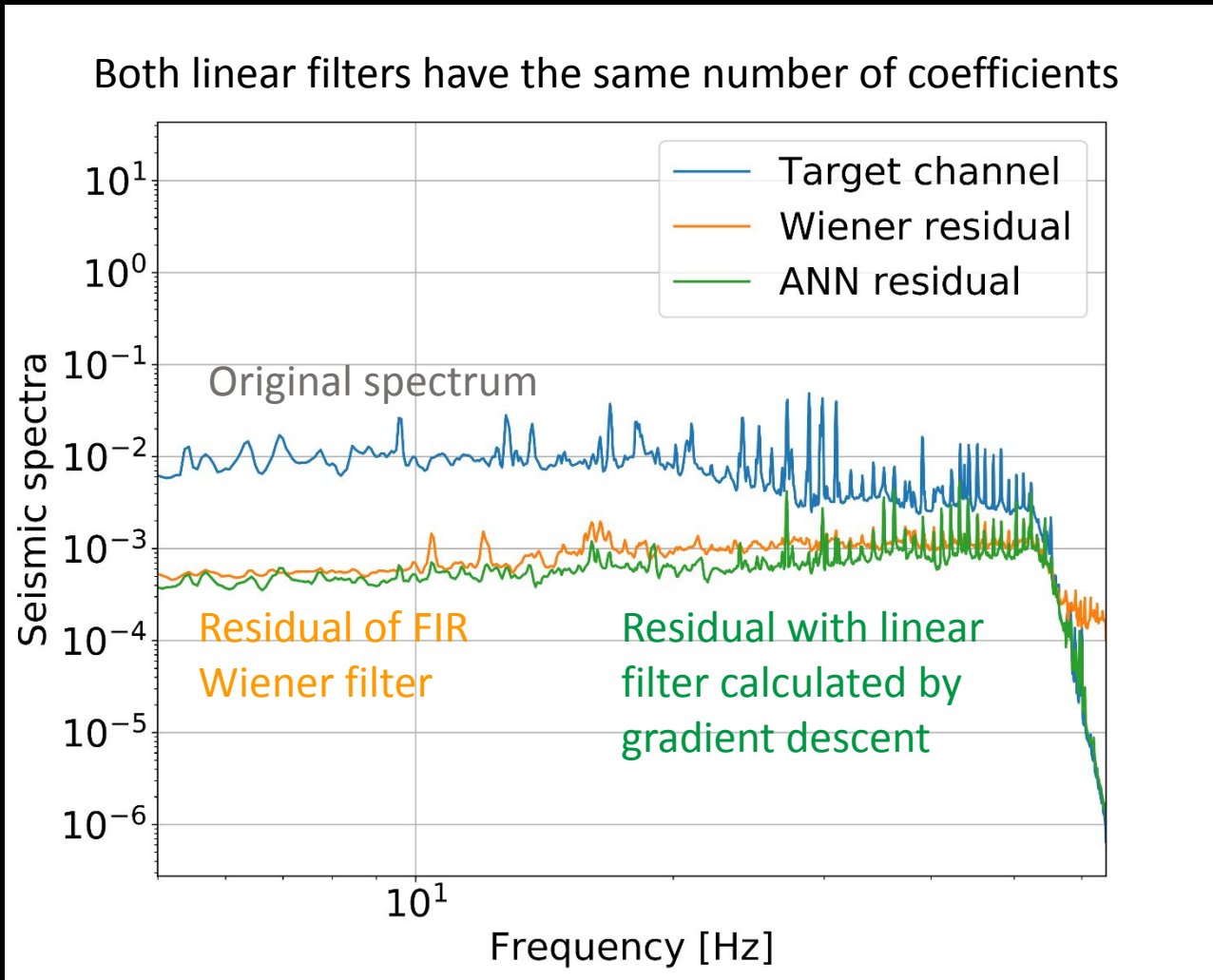
Noise subtraction

$$r_n = y_n - \mathbf{w} \circ \mathbf{x}_n$$

Alternative approaches:

- FIR with gradient descent
- Kalman filter
- Supervised ML

Filter designs

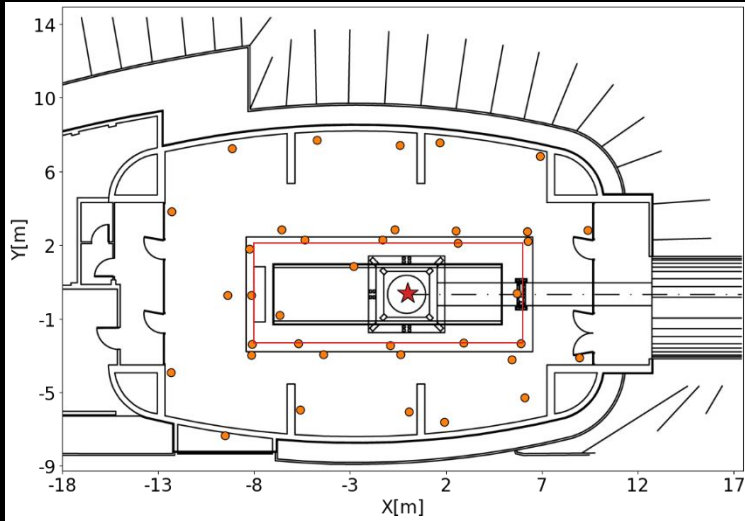


Wiener filter is the **optimal filter** for reduction of noise variance.

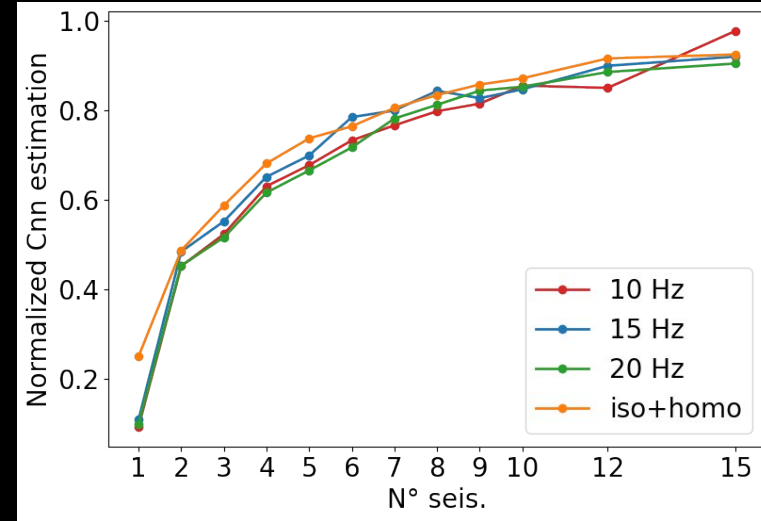
Reality: It depends on details. Statistical errors can limit how accurately we can calculate the Wiener filter.

Array Optimization

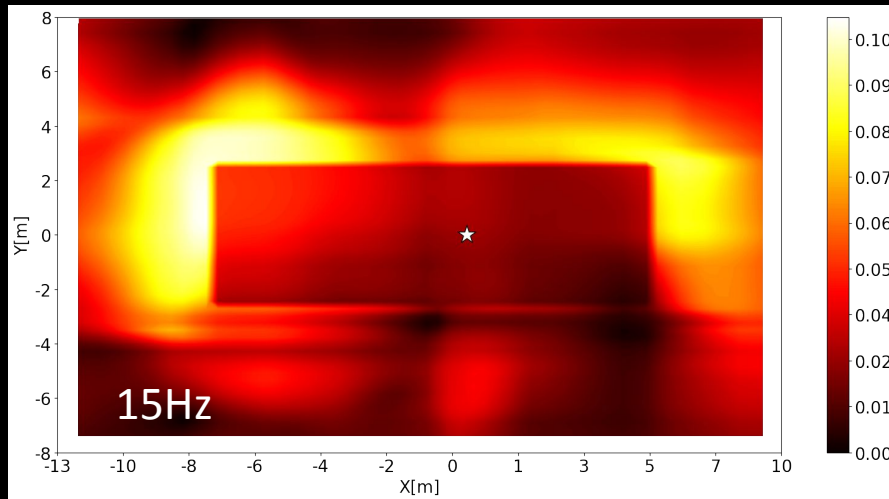
(1) Site characterization



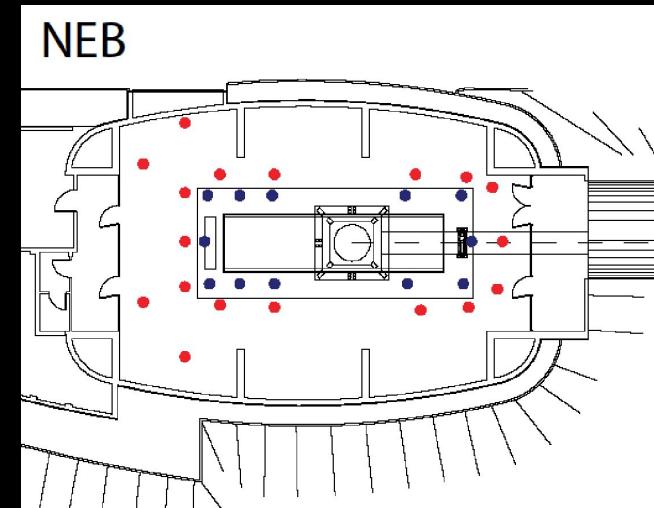
(3) Performance prediction



(2) Optimal seismometer placement

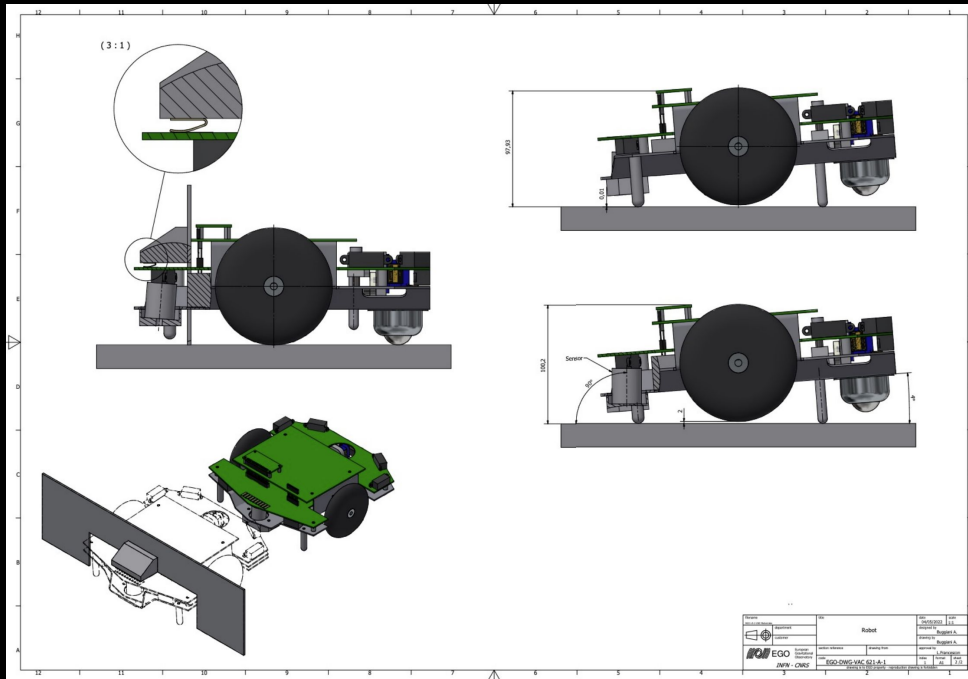
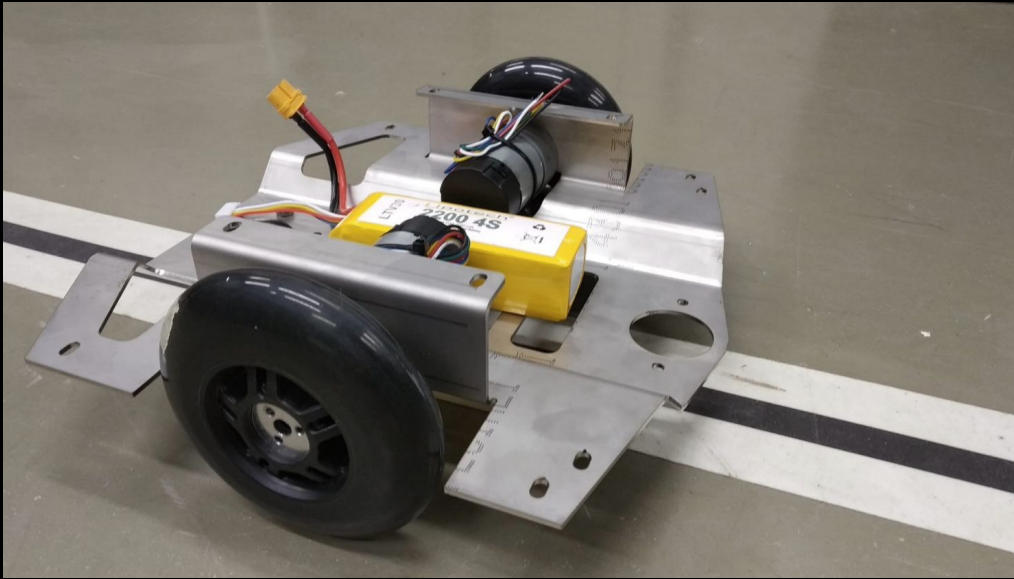


(4) Final array configuration at Virgo



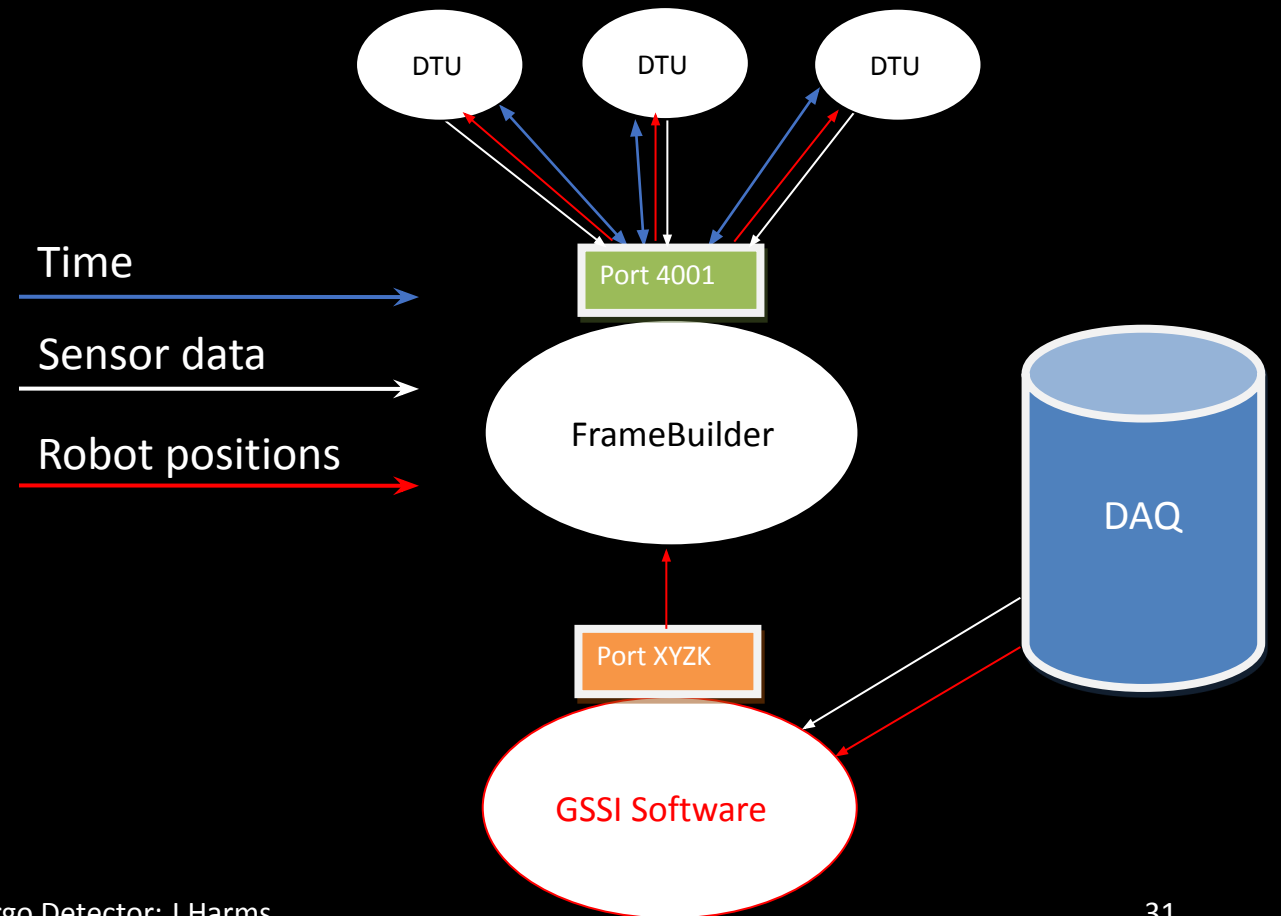
Robot platforms with seismic sensors

Use the same array-optimization algorithm in real time and converge to optimal array configuration.



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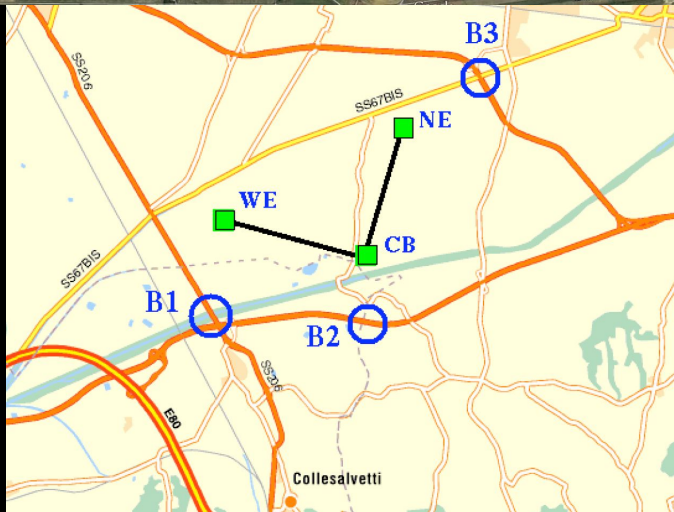
EGO robot team



The Virgo Detector; J Harms



Detector site

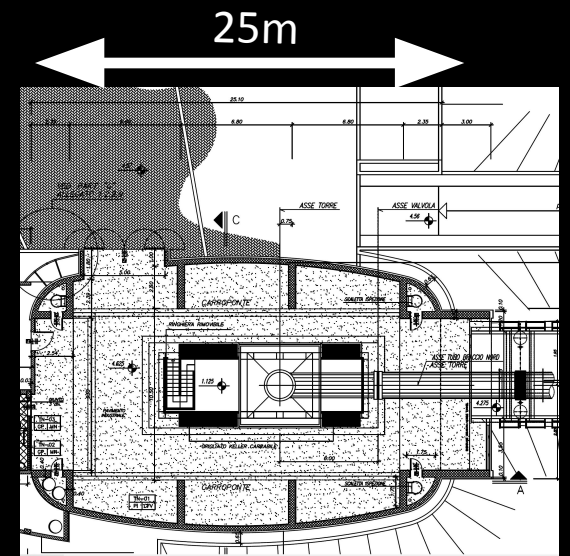
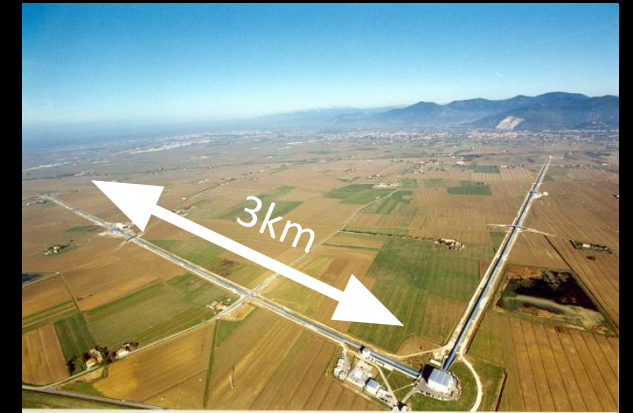


Infrastructure

Noise



Geometry



Optical layout (OptoCad)

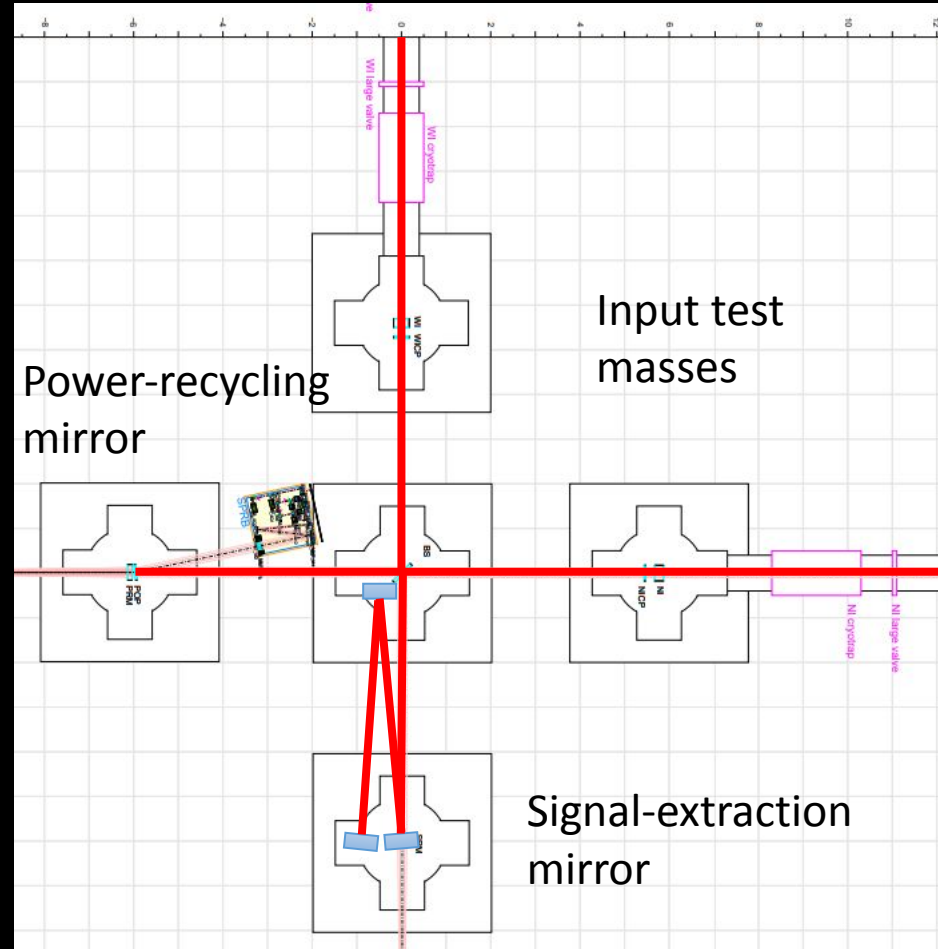
Virgo's Central Building is small



Distance between chambers cannot be increased



Limits the length of recycling cavities, and forces you into «riskier» solutions



Folded cavity (non-degenerate recycling cavity)



Multiple optics suspended inside BS and SE/PR towers



Eventually dismissed in favor of marginally-stable recycling cavities

CHRoCC: mirror curvature correction

One cannot operate the interferometer stably if the main optics have the wrong radius of curvature.

